

Curvature
without
calculus

Julie Carmela
La Corte

Motivation:
Classical
curvature
Normal curvature

Comparison
geometry
Metric spaces
Geodesic spaces
Nonpositive
curvature

Application:
Reconfig-
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systems

Curvature without calculus: An introduction to comparison geometry

Julie Carmela La Corte

University of Wisconsin–Milwaukee

November 20, 2014

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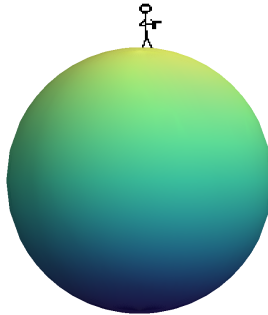
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Thought experiment:

The curvature of the Earth's surface at a point

Imagine a person standing on the Earth's surface and firing a magic bullet that is not affected by gravity.



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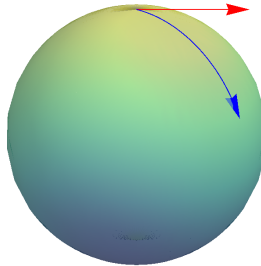
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Imagine a person standing on the Earth's surface and firing a magic bullet that is not affected by gravity.



The Earth's surface curves away from the bullet's trajectory.

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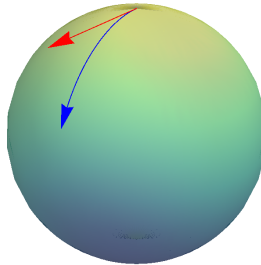
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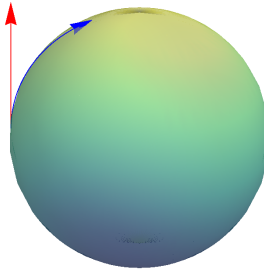


The Earth's surface curves away from the bullet's trajectory, no matter what direction the shooter faces.

Thought experiment:

The curvature of the Earth's surface at a point

Imagine a person standing on the Earth's surface and firing a magic bullet that is not affected by gravity.



The Earth's surface curves away from the bullet's trajectory, no matter what direction the shooter faces, and no matter where she stands.

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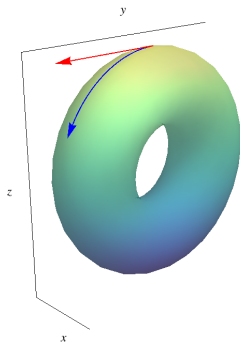
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Thought experiment:

The curvature of the torus at a point

The situation would be different if the surface of our planet was shaped like a torus.



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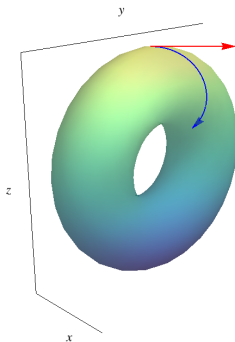
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Thought experiment:

The curvature of the torus at a point

The situation would be different if the surface of our planet was shaped like a torus.



A shooter standing at certain points of the torus would observe Earth-like curvature.

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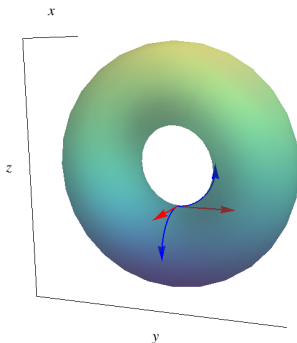
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Thought experiment:

The curvature of the torus at a point

The situation would be different if the surface of our planet was shaped like a torus.



But at a point on the inner rim of the torus, the shooter would see the torus curving away from the bullet's trajectory in some directions, and toward it in other directions.

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Normal vector to a surface

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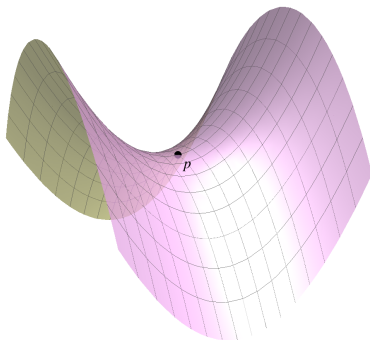
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A neighborhood of a point p on the inner rim of the torus resembles the *saddle surface*.

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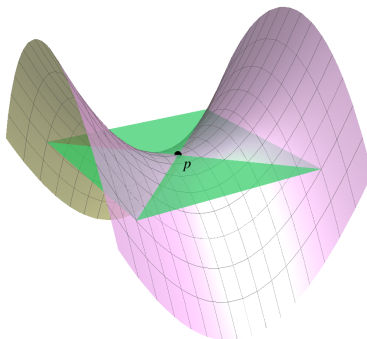
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A neighborhood of a point p on the inner rim of the torus resembles the *saddle surface*.

Let's draw a plane tangent to this surface at p .

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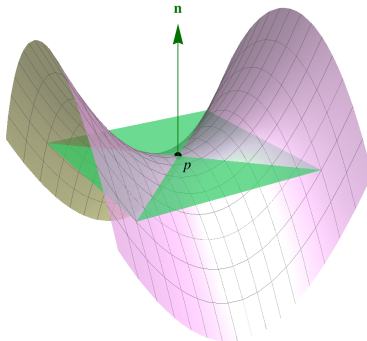
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A neighborhood of a point p on the inner rim of the torus resembles the *saddle surface*.

Let's draw a plane tangent to this surface at p .

Label one of the directions perpendicular to the tangent plane as **n**. This direction will be called "up."

Negative curvature at a point on a surface

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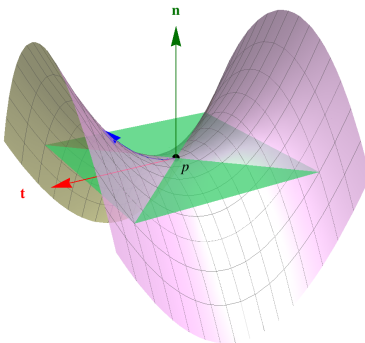
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For certain initial directions \mathbf{t} , curves along the saddle surface that start at p bend “up,” toward \mathbf{n} .

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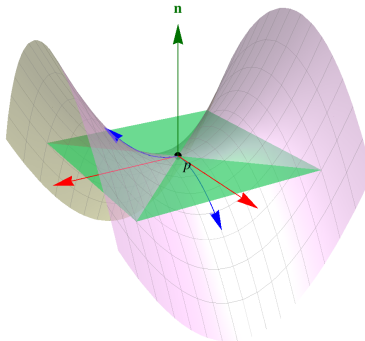
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For certain initial directions \mathbf{t} , curves along the saddle surface that start at p bend “up,” toward \mathbf{n} .

For other choices of \mathbf{t} , they bend “down,” away from \mathbf{n} .

We say that such a point p is **hyperbolic**, and that the surface is **negatively curved** at p .

Negative curvature at a point on a surface

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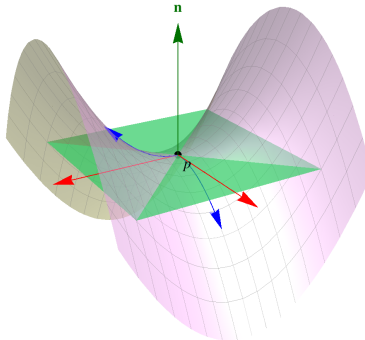
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For other choices of \mathbf{t} , they bend “down,” away from \mathbf{n} .

We say that such a point p is **hyperbolic**, and that the surface is **negatively curved** at p .

Positive curvature at a point on a surface

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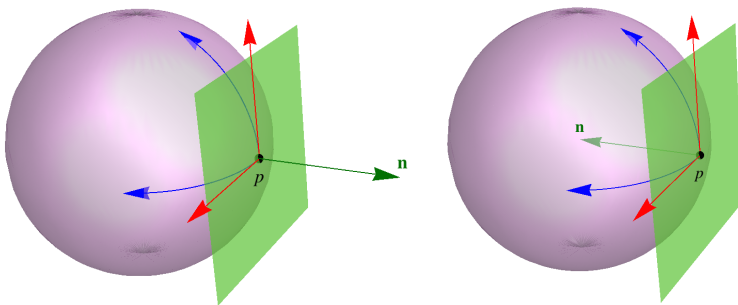
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A surface is **positively curved** at a point p , and p is an **elliptic point**, if:

- for any choice of initial direction \mathbf{t} , all curves along the surface starting at p bend toward \mathbf{n} , or all bend away from \mathbf{n} .

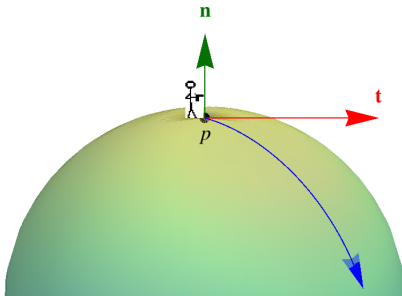


Normal curvature

In calculus, we learn that the **normal curvature**

$$\kappa = \kappa(\mathbf{t})$$

measures how quickly a surface appears to bend in a given direction \mathbf{t} when standing at a point p on the surface.



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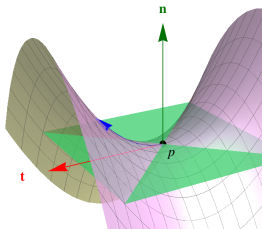
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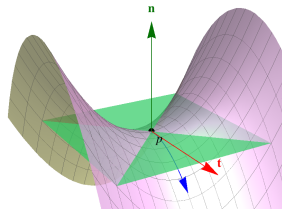
$$\kappa = \kappa(\mathbf{t})$$

measures how quickly a surface appears to bend in a given direction \mathbf{t} when standing at a point p on the surface.

- If $\kappa > 0$, the surface bends in the direction of \mathbf{n} .
- If $\kappa < 0$, the surface bends in the opposite direction.



$$\kappa(\mathbf{t}) > 0$$



$$\kappa(\mathbf{t}) < 0$$

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Computing the normal curvature κ isn't hard, but it can be tedious...

Write $\mathbf{t} = \begin{bmatrix} du \\ dv \end{bmatrix}$. Then

$$\kappa\left(\begin{bmatrix} du \\ dv \end{bmatrix}\right) = -\frac{\left(\frac{\partial \mathbf{x}}{\partial u} \cdot \frac{\partial \mathbf{n}}{\partial u}\right) du^2 + \left(\frac{\partial \mathbf{x}}{\partial u} \cdot \frac{\partial \mathbf{n}}{\partial v} + \frac{\partial \mathbf{x}}{\partial v} \cdot \frac{\partial \mathbf{n}}{\partial u}\right) du dv + \left(\frac{\partial \mathbf{x}}{\partial v} \cdot \frac{\partial \mathbf{n}}{\partial v}\right) dv^2}{\left(\frac{\partial \mathbf{x}}{\partial u} \cdot \frac{\partial \mathbf{x}}{\partial u}\right) du^2 + 2\left(\frac{\partial \mathbf{x}}{\partial u} \cdot \frac{\partial \mathbf{x}}{\partial v}\right) du dv + \left(\frac{\partial \mathbf{x}}{\partial v} \cdot \frac{\partial \mathbf{x}}{\partial v}\right) dv^2},$$

where

$$\mathbf{n} = \mathbf{n}(u, v) = \frac{\frac{\partial \mathbf{x}}{\partial u} \times \frac{\partial \mathbf{x}}{\partial v}}{\left| \frac{\partial \mathbf{x}}{\partial u} \times \frac{\partial \mathbf{x}}{\partial v} \right|}.$$

 *Moral:* Calculus provides effective tools for describing the curvature of a surface, but requires lots of calculation.

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 *Moral:* Calculus provides effective tools for describing the curvature of a surface, but requires lots of calculation.

Curvature in n -dimensional spaces ($n \geq 3$)

It makes sense to speak of the curvature of higher-dimensional geometric figures, too, although the mathematics is much more difficult.

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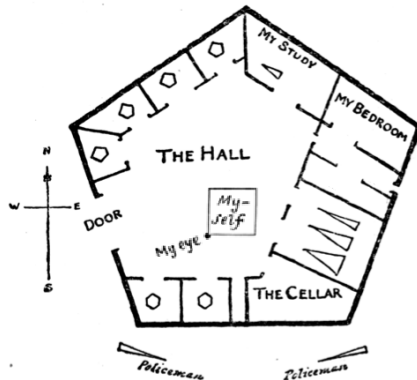
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It makes sense to speak of the curvature of higher-dimensional geometric figures, too.

☞ To a topologist, the sphere, the torus, and the saddle surface are *2-dimensional spaces*.



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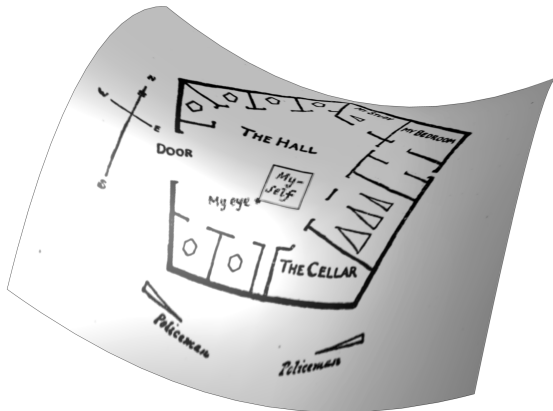
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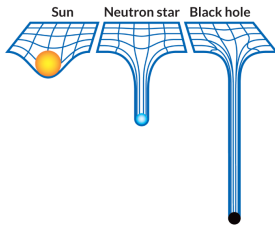
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It makes sense to speak of the curvature of higher-dimensional geometric figures, too.

The theory of general relativity tells us that our universe, which we experience as being 3-dimensional, is “curved” in the vicinity of massive objects.



The curvature of n -dimensional shapes for $n \geq 3$ is studied in the branch of mathematics known as **differential geometry**.

Curvature in n -dimensional spaces ($n \geq 3$)

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The curvature of n -dimensional spaces for $n \geq 3$ is studied in the branch of mathematics known as **differential geometry**.

 As we look at spaces of higher and higher dimension, we need more and more calculations to characterize their curvature.

Why comparison geometry?

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Comparison geometry is an alternative method for describing the curvature of a space.

- *It's simple:*
No calculus (or differential geometry) is required.
- *It scales well:*
Exactly the same amount of work is required to describe the curvature of a space of *any* dimension.
- *It's purely geometric:*
Comparison geometry is based on triangles and distances.
- *Minimal prerequisites:*
Just 4 axioms are required to do comparison geometry.

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The first three axioms define *distance*.

- Given any geometric figure (any set, even), we can define what the distance between two points is.

A **distance function** on a set X is a function $d : X \times X \rightarrow [0, \infty)$ satisfying the following axioms.

- $d(x, x) = 0$ for all x in X .
- $d(x, y) = d(y, x)$ for all x and y in X .
- $d(x, z) \leq d(x, y) + d(y, z)$ for all x, y, z in X .
You can't take a shortcut from x to z by going through y .

A **metric space** is a set X together with a distance function on X .

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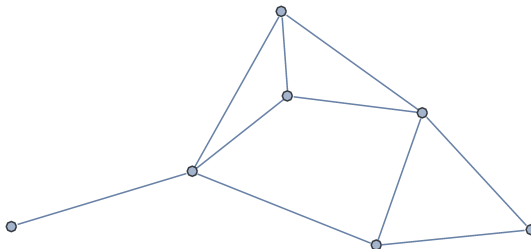
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Metric spaces

Examples of metric spaces:

■ Graphs



Curvature
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calculus

Julie Carmela
La Corte

Motivation:
Classical
curvature

Normal curvature

Comparison
geometry

Metric spaces

Geodesic spaces

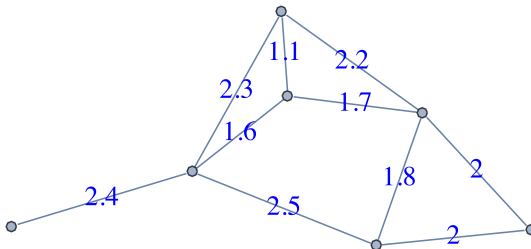
Nonpositive
curvature

Application:
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systems

Metric spaces

Examples of metric spaces:

■ Graphs



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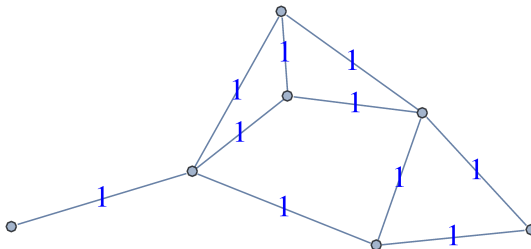
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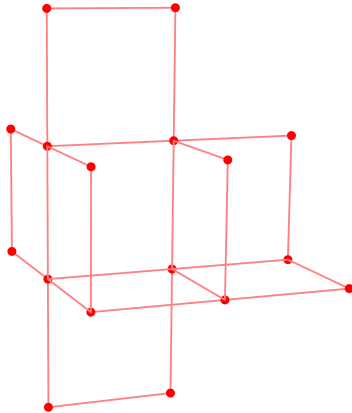
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Examples of metric spaces:

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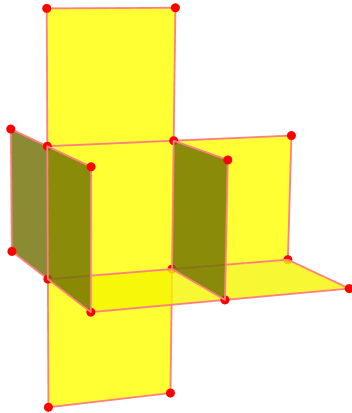
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Metric spaces

Examples of metric spaces:

- Square complexes



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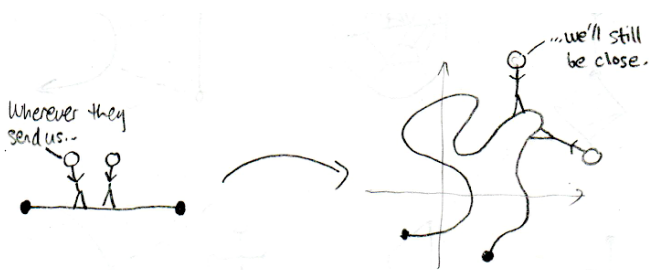
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Paths

A **path** in a space X is a continuous function from the unit interval to X .

That is, nearby points are sent to nearby points.



A shortest path between two points x and y is called a **geodesic path** between x and y .

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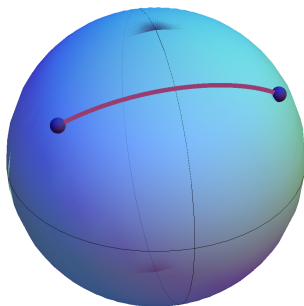
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4th axiom:

A metric space X is called a **geodesic space** if there is a (t least one) shortest path between any two points in X .

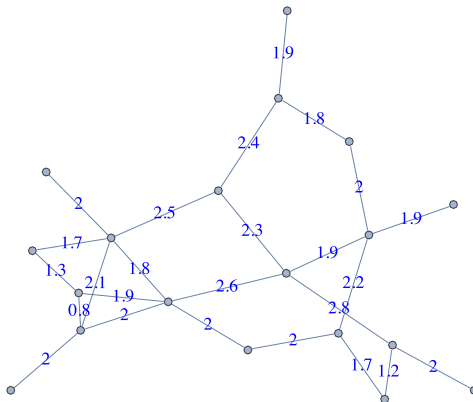
Example of a geodesic space:

- Sphere



Geodesic paths

Example of a geodesic space:



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Geodesic triangles

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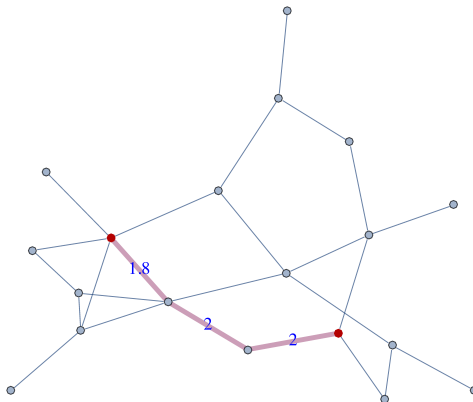
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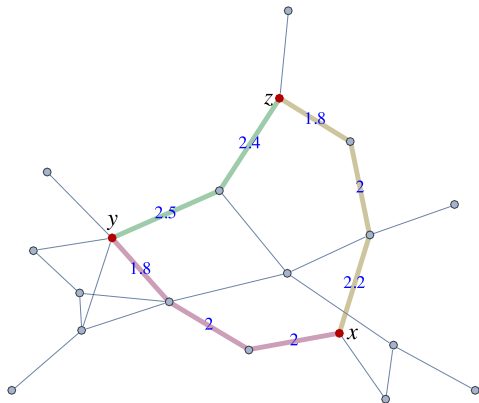
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A **geodesic triangle** Δxyz is a “triangle” whose sides are geodesic paths joining x , y , and z in pairs.

Comparison triangles

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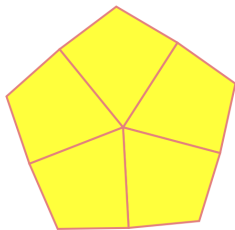
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We can describe the curvature of a space using only triangles.

Suppose Δxyz is a geodesic triangle in a metric space. A **comparison triangle** $\Delta x'y'z'$ is a triangle in the (Euclidean) plane with corresponding sides equal in length.

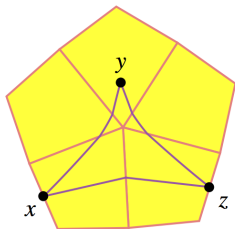


See cardboard model. . .

Comparison triangles

We can describe the curvature of a space using only triangles.

Suppose Δxyz is a geodesic triangle in a metric space. A **comparison triangle** $\Delta x'y'z'$ is a triangle in the (Euclidean) plane with corresponding sides equal in length.



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Comparison triangles

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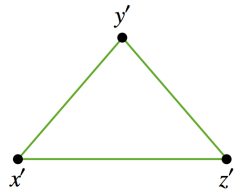
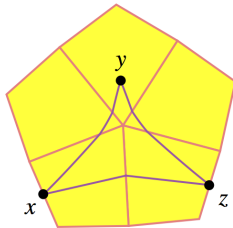
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We can describe the curvature of a space using only triangles.

Suppose Δxyz is a geodesic triangle in a metric space. A **comparison triangle** $\Delta x'y'z'$ is a triangle in the (Euclidean) plane with corresponding sides equal in length.



Nonpositive curvature: The “thin triangles” definition

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A geodesic triangle Δxyz is **thin** if the distance between any two points on Δxyz is no larger than the distance between the corresponding points on a comparison triangle:

$$d(p, q) \leq d(p', q').$$

We say that a geodesic space is **nonpositively curved (NPC)** at a point w if all geodesic triangles sufficiently near w are thin.

In a **nonpositively curved** space, all geodesic triangles are thin.

Nonpositively curved spaces

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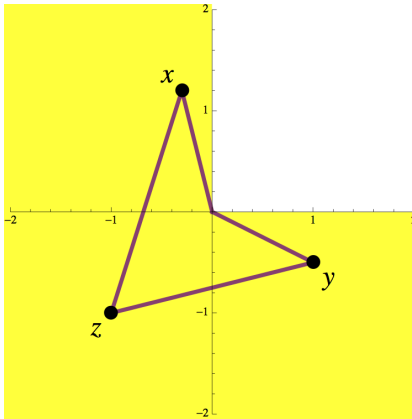
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Examples of nonpositively curved spaces:

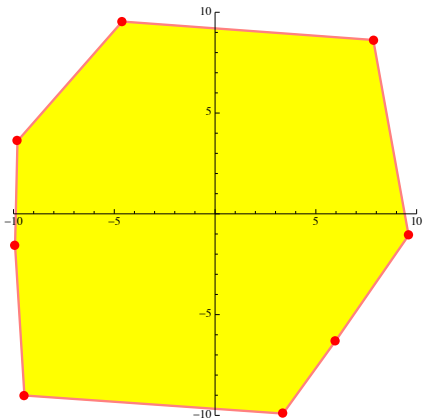
- The Cartesian plane with Quadrant I removed



Nonpositively curved spaces

Examples of nonpositively curved spaces:

- Convex subsets of the plane



Curvature
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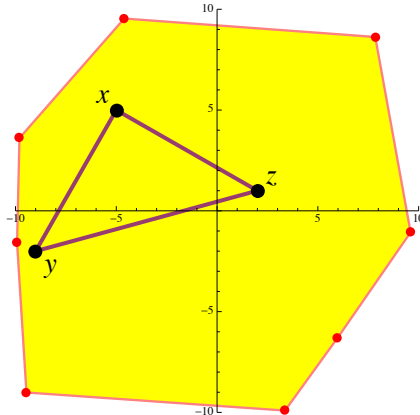
Nonpositive
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Nonpositively curved spaces

Examples of nonpositively curved spaces:

- Convex subsets of the plane



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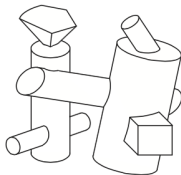
Geodesic spaces

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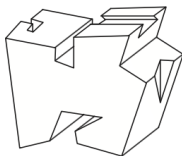
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Examples of nonpositively curved spaces:

- Unions of convex sets glued along convex subsets



- Cylindrically deleted cubes



Nonpositive curvature: The “pointy angles” definition

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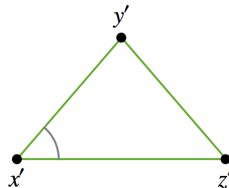
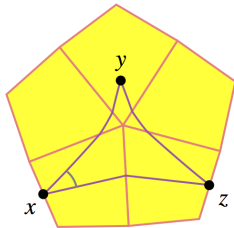
Geodesic spaces

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An alternative way to characterize nonpositively curved spaces:

A geodesic triangle is **pointy** if the angle between any two of its sides is no larger than the corresponding angle of a comparison triangle.



A geodesic space is **nonpositively curved (NPC)** near a point w if all triangles sufficiently near w are pointy.

Nonpositive curvature: The “pointy angles” definition

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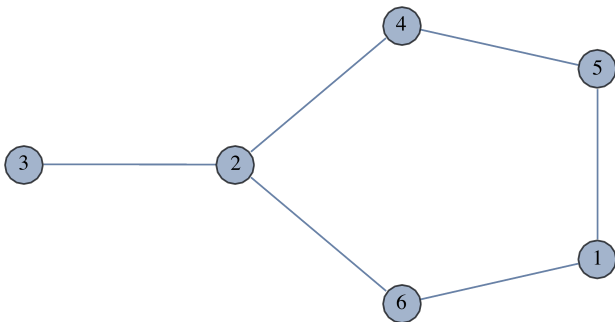
Geodesic spaces

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More examples:

- A graph is nonpositively curved at every point.



Nonpositive curvature: The “pointy angles” definition

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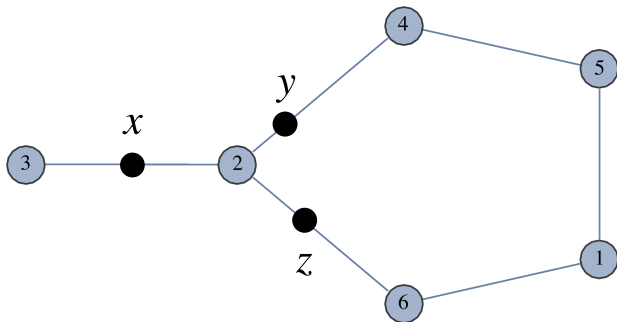
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Nonpositive curvature: The “pointy angles” definition

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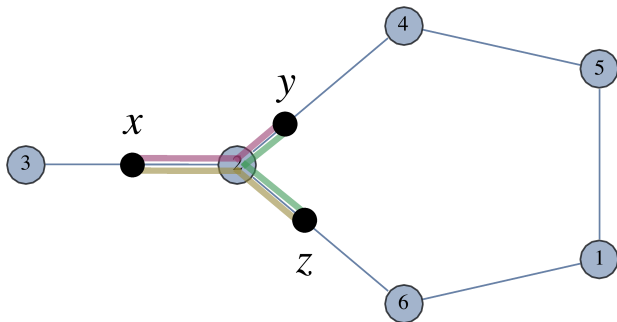
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Gromov's Link Condition

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Consider a surface made up of n equilateral triangles arranged cyclically around a central vertex v .

When $n = 5$, the surface contains “fat” triangles.

Do any of the surfaces we saw today contain fat triangles?

Gromov's Link Condition.

- A surface made up of n equilateral triangles arranged cyclically around a central vertex v is nonpositively curved at v if and only if. . .

What is comparison geometry good for?

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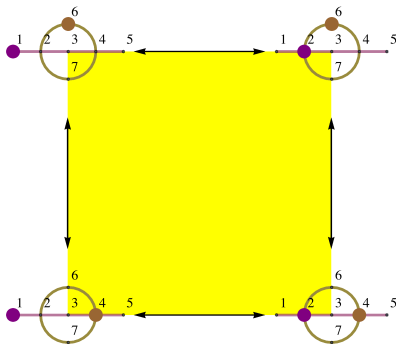
Comparison geometry has practical applications to robotics, chemical engineering, biology. . .

For example, many robotic systems can be modeled by nonpositively curved cube complexes.

Two robots moving along tracks on a factory floor

State complex

Every point in the **state complex** corresponds to a possible configuration of the system.



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Shape-changing robots

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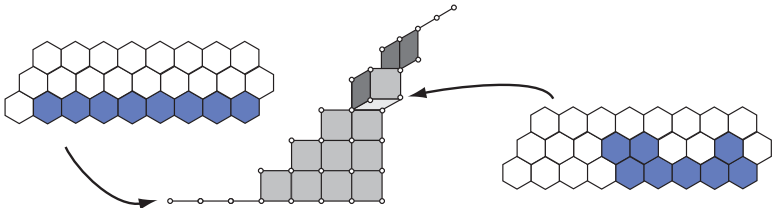
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Every point in the **state complex** corresponds to a possible configuration of the system.



State complex for a metamorphic robotic system
composed of pivoting hexagonal tiles

Planning a change of state

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Paths in the state complex correspond to reconfiguration strategies.

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- All computer-generated pictures and animations created in Mathematica except where noted.